

Procedure *INIT-PATH*
 {Invoked when the node comes up.}

1. Initialize all tables.
2. Run *PATH* algorithm.

End *INIT-PATH*

Algorithm *PATH*

{Invoked when a message M is received from neighbor k ,
 or an adjacent link to k has changed or when a node is
 initialized }

1. Run *NTU* to update neighbor tables.
2. Run *MTU* to update main tables.
3. For each destination j marked as *changed*,
 Add update entry $[j, D_j^i, p_j^i]$ to the new message M' .
4. Within finite amount of time, send message M' to
 each neighbor.

End *PATH*

Procedure *NTU*

{Called by *PATH* to process an event. }

1. If event is a message M from neighbor k ,
 a. For each entry $[i, d, p]$ in M //Note $d = D_k^i, p = p_k^i$

Set $D_{jk}^i \leftarrow d$ and $p_{jk}^i \leftarrow p$

- b. For each destination j with an entry in M ,

Remove existing links (n, j) in T_k^i and add new
 link (m, j, d) to T_k^i , where $d = D_{jk}^i - D_{mk}^i$
 and $m = p_{jk}^i$.

2. If the event is an adjacent link-status change, update I_k^i and
 clear neighbor tables of k , if link is down.

End *NTU*

FIG. 1

FIG. 2

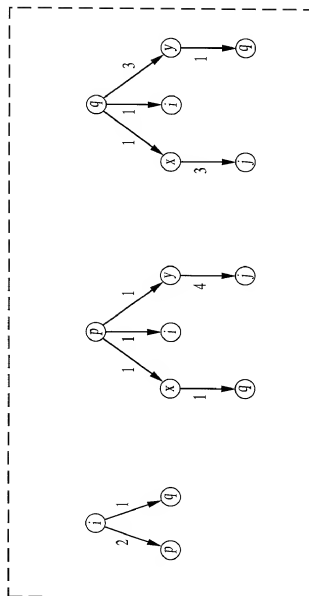
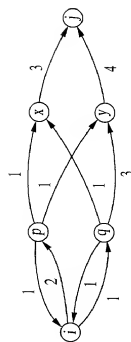


FIG. 3A



Preferred Neighbors

Destination	p	q	x	y	j
Distance	2	1	2	3	5
Pref. Nbr	p	q	q	p	q

FIG. 3B

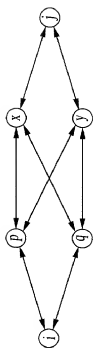


FIG. 4A

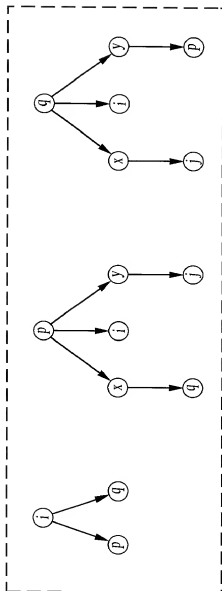


FIG. 4B

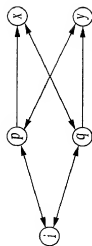


FIG. 4C

Procedure *MTU*

1. Clear link table T^i .
2. For each node $j \neq i$ occurring in at least one T^i :
 - a. Find $MIN \leftarrow \min \{D_{ij} + l_{ij} \mid k \in N\}$.
 - b. Let a be such that $MIN = (D_{ia} + l_{ia})$. Ties are broken *consistently*. Neighbor a is the preferred neighbor for destination j . For each link (j, v, d) in T^i :
Add link (j, v, d) to T^i .
3. Update T with each link l_{ij} .
4. Run Dijkstra's shortest path algorithm on T^i to find new D_j^i , and P_j^i .
5. For each destination j , if D_j^i or P_j^i changed from previous value, set *changed* and *report-it* flags for j .

End *MTU*

FIG. 5

Procedure *INIT-MPATH*

{*Invoked when the node comes up.*}

1. Initialize tables and run *MPATH*.

End *INIT-MPATH*

Algorithm *MPATH*

{*Invoked when a message M is received from neighbor k , or an adjacent link to k has changed.*}

1. Run *NTU* to update neighbor tables.
2. Run *MTU* to obtain new D_j^i and p_j^i .
3. If node is *PASSIVE* or node is *ACTIVE* \wedge last reply arrived,

Reset *goactive* flag.

For each destination j marked as *report-it*,

- a. $FD_j^i \leftarrow \min\{D_k^i, RD_j^i\}$
- b. If $D_j^i > RD_j^i$ Set *goactive* flag.
- c. $RD_j^i \leftarrow D_j^i$
- d. Add $[j, RD_j^i, p_j^i]$ to message M' .
- e. Clear *report-it* flag for j .

Otherwise, the node is *ACTIVE* and waiting for more replies,

For each destination j marked as *changed*,

- f. $FD_j^i \leftarrow \min\{D_j^i, FD_j^i\}$

4. For each destination j marked as *changed*,

a. Clear *changed* flag for j

- b. $S_j^i \leftarrow \{k | D_{jk}^i < FD_j^i\}$

5. For each neighbor k ,

a. $M'' \leftarrow M'$

b. If event is *query* from k , Set *reply* flag in M'' .

c. If *goactive* set, Set *query* flag in M'' .

d. If M'' non-empty, send M'' to k .

6. If *goactive* set, become *ACTIVE*, otherwise become *PASSIVE*.

END *MPATH*

FIG. 6